

**TREX** ENTERPRISES  
CORPORATION

# 76-81 GHz Automotive Radar

Design for Interoperability in Densely-Trafficked Environments

Presented by:

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Presented to:

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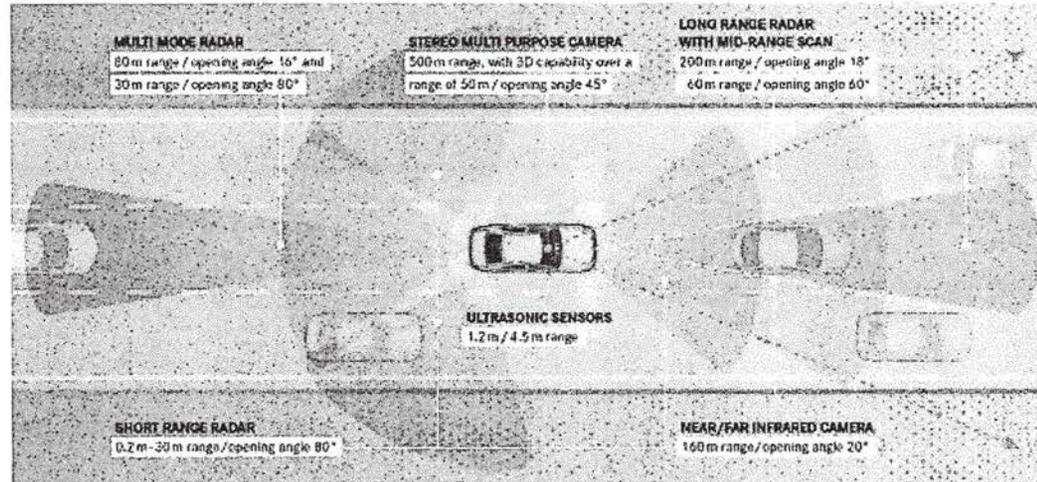
November 20, 2015

# Discussion Outline

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- ◆ **Automotive Radar Interoperability Issues**
  - Vision for Wrap-Around Protective Radar “Halo” on All Vehicles Creates a Very Dense Interference Environment
- ◆ **Impacts of Recent Advance in Silicon CMOS Processing**
  - Potentially Disruptive Cost with a “New” Auto Radar Architecture
- ◆ **PMCW Radar Characteristics / Contrast with FMCW**
  - Interoperability Considerations Specific to Coded Spread Spectrum Approaches
- ◆ **Future Standards for Protecting Auto Radar Interoperability**
  - Understanding the Envelope for Innovation in a Potentially Crowded Market (and Spectrum)
- ◆ **Status Review of the FCC 77-81 GHz NPRM**

# Fundamental Radar Interference Challenge



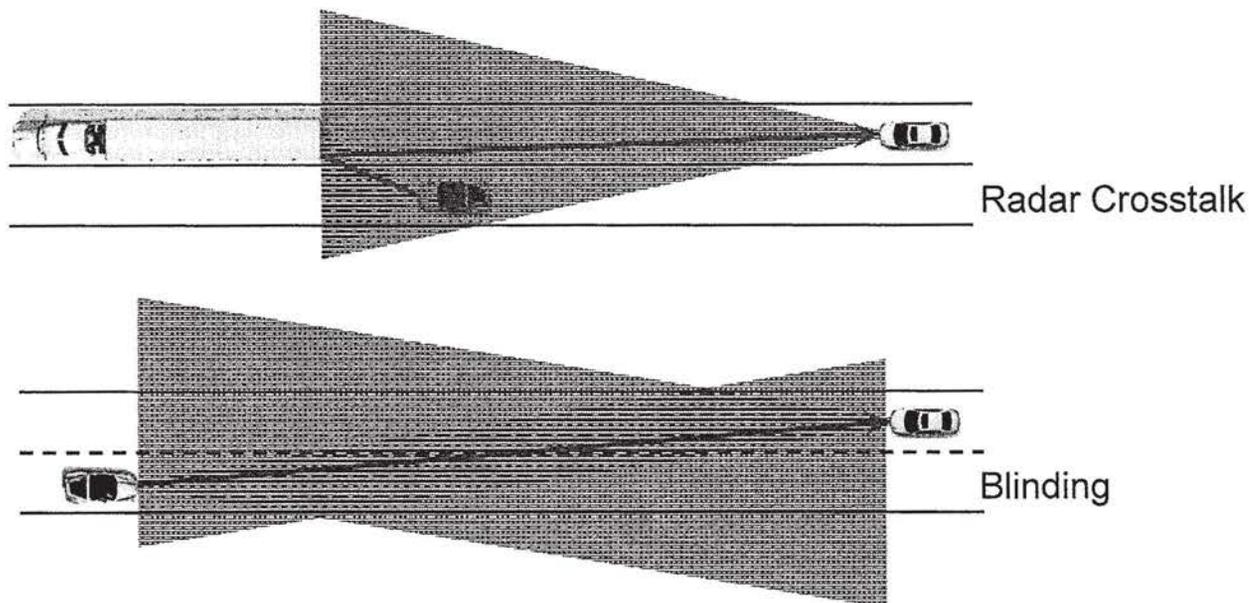
Source: Bleckmanan, Novedades, Technologia 5/6/13

## ◆ Lots of Radars on the Road...

- Forward Facing Long-Range Radar (76.5 GHz) and Mid-Range Radar (76.5 or 79 GHz) on Every Car
- Rear-Facing Multi-Mode Radar (79 GHz), on High-end Cars
- Corner Short-Range Radars (79 GHz), on High-end Cars

## ◆ In Bumper-to-bumper Traffic, Forward- and Backward-Facing Radars will Transmit into One Another from Point-blank Range

## Other Common Interference Challenges



### ◆ Automotive Radars Will Interact in Different Ways

- e.g. FMCW-on-FMCW, FMCW-on-PMCW, Scanned-beam-on-MIMO

### ◆ Radar Manufacturers Can Prevent Self- or Like-type Interference through Judicious Systems Engineering

- Managing radar beamwidth, direction and/or power dynamically
- Coordinating antenna polarizations and/or employing MRR/SRR band segmentation
- Offsetting FMCW chirps or orthogonalizing PMCW codes

### ◆ In Absence of Standards, New Market Entrants Can Negate Such Efforts

# Dynamic Range Requirements

## ◆ Automotive Radar Receiver Sees ~180 dB of Dynamic Range

- To limit distortion, tasks must be divided into smaller ranges of target distance
- Assume LRR is in separate band (existing 77 GHz Allocation)
- Forward SRR/MRR and Rear-Facing MRR Radar will share the 77-81 GHz Radar Band

Function	Range (m)		$\sigma$ (dBm <sup>2</sup> )		Dynamic Range (dB)	Radar Frequency (GHz)
	Min	Max	Min	Max		
LRR	30	320	0	40	81	76.5
MRR	5	30	-10	40	81	79*
SRR	1	6	-10	40	81	79*
Parking	0.2	1.2	-10	40	81	79*

$$\text{Dynamic Range} = 40 \log_{10} \left( \frac{R_{max}}{R_{min}} \right) + (\sigma_{max} - \sigma_{min})$$

\*Could Be Subdivided, by Rule or by Convention

# New Development in Silicon CMOS

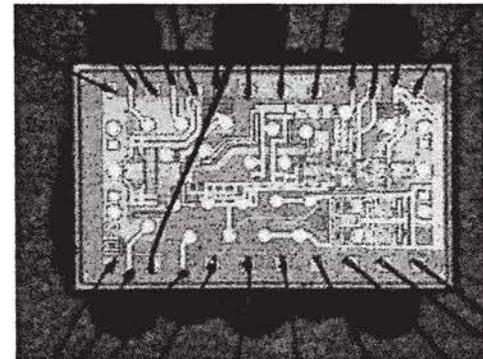
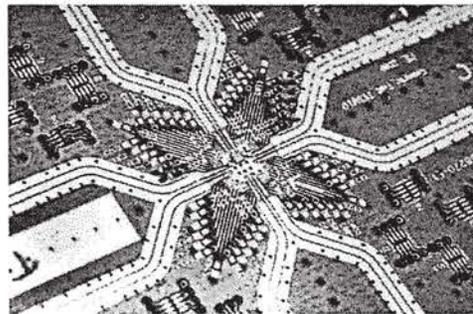
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## ◆ Single-Chip 79 GHz PMCW Radar Transceiver Produced with 28 nm Lithography on Bulk-Silicon CMOS

- Record Efficiency (~10%) and Low-Cost (~\$0.25), not attainable using emergent SiGe technology
- First Published in IEEE Journal of Solid State Circuits, Vol. 49, No. 12, December 2014

## ◆ Chip Comprises the Entire Transceiver Front End:

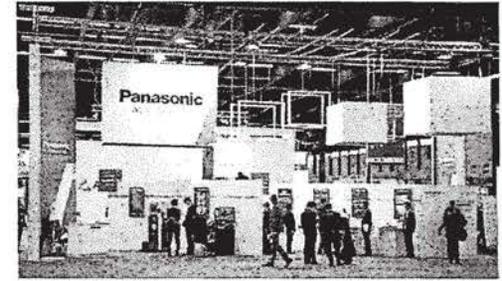
- Receiver LNA with 7 dB NF
- Transmitter PA with +11 dBm output power
- 5x Multiplier for 15.8 GHz external LO (79 GHz radar carrier)
- 2 Gbps BPSK signal modulator/demodulator at 79 GHz



# “New” Radar Architecture

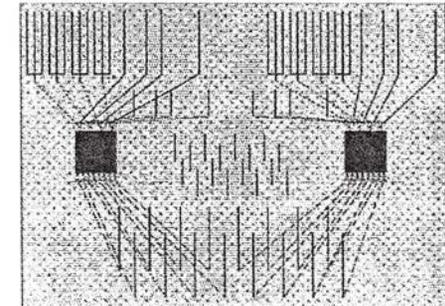
## ◆ Phase-Modulated Continuous Wave Radar

- Currently under development at Panasonic, under investigation at Magna
- Coded BPSK waveform, similar to CDMA, GPS (spread spectrum)
- Occupied Bandwidth Depends upon Modulation Rate, e.g.:
  - LRR: 76.25-76.75 GHz
  - MRR: 78.5-79.5 GHz
  - SRR: 77.5-80.5 GHz
- Interference Susceptibility Dependent upon Code Type



## ◆ MIMO Antenna Array

- Low EIRP (~5 dBW), Digital Beamforming
- Channel Orthogonality Dependent upon Code Type
- ~70 cm<sup>2</sup> Combined Antenna Aperture Multi-Function (Long-, Mid- and Short-Range) Radar
- Larger Distributed Apertures also Possible in Future



## ◆ Pertinent to Front, Corner, and Rear-Facing Radars

- High-End and Mass Market Radars using Single-Chip Transceiver Arrays

# PMCW Characteristics Compared to FMCW

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## ◆ FMCW is Essentially “Incumbent” in this Space

- Pulse compression is performed in frequency space
  - Narrowband instantaneous transmission, “spread spectrum” only when averaged over slower chirp period
  - Potential interference involves probability of chirp collisions (duty cycle)
- Log amp reduces IF dynamic range requirements
- Linearity of sweep module (“chirp”), LO phase noise and bit depth of (post-compression) digitizer drive cost

## ◆ PMCW is Not Technically a New Approach, but Will Be Newer to the Automotive Radar Space

- Pulse compression is performed temporally, using a matched filter
  - BPSK modulation at 1-2 Gcps; “spread spectrum” in the true sense of the phrase
  - Potential interference involves probability of code collisions (design criterion)
- High IF dynamic range requirements
  - Coding gain from long matched filter drops digitizer bit depth requirement relative to FMCW, but increases digitizer speed requirement
- No significant cost drivers

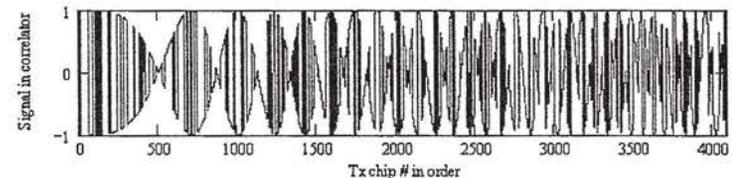
# PMCW MIMO Radar Interference: Intrusiveness and Susceptibility

## ◆ Interference from MIMO PMCW Radar

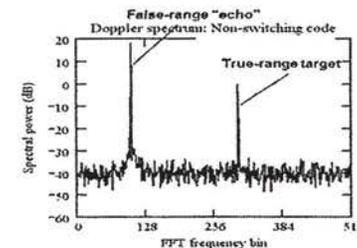
- True spread spectrum (low instantaneous PSD) is maximally benign to all similar and non-similar radar approaches
- Non-scanning MIMO antenna, with digital beamforming (low instantaneous irradiance / EIRP) is maximally benign to all antenna types

## ◆ Interference to MIMO PMCW Radar

- Very slow scanning FMCW radar (tone-like emitter) could create false targets
  - Not likely given update rate requirements for automotive radar
  - Modeling suggests that existing FMCW radar causes no performance degradation to PMCW
- Auto- and Cross-Correlation sidelobes from host and other PMCW radars could create false targets
  - Interference susceptibility can be mitigated by proper code selection and cycling
  - A poor “first to market” PMCW design could limit performance and restrict future market entry



PMCW Chirp Averages to Zero in Correlator



# How Will Auto Radar Interoperability Be Enforced?

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## ◆ ECC/ITU has Identified SRR in 77-81 GHz as Operating on a “Non-interference and Non-protected Basis”

- “No harmful interference may be caused to other users of the band and no claim may be made for protection from harmful interference received from other systems” [2004/545/EC]
- Seems there is nothing to enforce here – how can this be the basis for a safety-of-life feature that will soon be mandated for all vehicles?
- A better approach might be something similar to PCI-SIG “Plug-Fest,” where new products must first prove harmonious interoperability with radars already on the road

## ◆ ECC/ITU Emissions Limits:

- 25 dBW EIRP peak
- -9 dBm/MHz mean PSD radiated outside of vehicle

## ◆ Typical PMCW Radar:

- 5 dBW EIRP peak
- -14 dBm/MHz mean PSD radiated outside of vehicle
- Modeling suggests that PMCW is fully harmonious with FMCW
  - However, e.g., narrowband tone emissions could be harmful to both

# FCC NPRM and Rulemaking Timeline

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- ◆ **Trex has seen and read the NPRM and subsequent comments**
- ◆ **Trex resonates with Bosch reply comments regarding restricting LRR operations to 76-77 GHz band**
  - Although definition of LRR operations needs further detail
- ◆ **Trex is engaging in R&D work associated with future automotive radar technology**
  - ... and therefore seeks clarification on the current status and timeline for the FCC Rulemaking process related to 77-81 GHz
  - ... as well as an “on-ramp” for participating in future FCC/Industry discussions related to this Rulemaking



**Thank You!**